

ECE171A: Linear Control System Theory

Lecture 10: Frequency Response

Instructor:

Nikolay Atanasov: natanasov@ucsd.edu

Teaching Assistant:

Chenfeng Wu: chw357@ucsd.edu

UC San Diego

JACOBS SCHOOL OF ENGINEERING
Electrical and Computer Engineering

Frequency Response

- ▶ Consider a control system with input $R(s)$, output $Y(s)$, and transfer function $G(s)$
- ▶ Consider an exponential test signal defined by $s_0 = \sigma + j\omega$:

$$R(s) = \frac{1}{s - s_0} \quad r(t) = \mathcal{L}^{-1} \left\{ \frac{1}{s - s_0} \right\} = e^{s_0 t}, \quad t \geq 0$$

- ▶ The system response is:

$$\begin{aligned} y(t) &= \mathcal{L}^{-1} \{ G(s)R(s) \} = (g * r)(t) = \int_0^t g(\tau)r(t - \tau)d\tau \\ &= e^{s_0 t} \left[\int_0^t g(\tau)e^{-s_0 \tau} d\tau \right] \end{aligned}$$

- ▶ As $t \rightarrow \infty$, $\left[\int_0^t g(\tau)e^{-s_0 \tau} d\tau \right] \rightarrow \mathcal{L} \{ g(t) \} = G(s_0)$
- ▶ The steady-state response to $r(t) = e^{s_0 t}$ is:

$$y_{ss}(t) = G(s_0)e^{s_0 t}$$

Frequency Response

- ▶ Applying the test signal $r(t) = e^{s_0 t}$ for different s_0 gives us a way to identify the transfer function $G(s)$ of an unknown system using the steady-state response:

$$y_{ss}(t) = G(s_0)e^{s_0 t}$$

- ▶ How do we apply $r(t) = e^{s_0 t}$ in practice?
- ▶ If $\text{Re}(s_0) > 0$ or $\text{Re}(s_0) < 0$, the system response either blows up or decays very quickly.
- ▶ Consider $s_0 = j\omega$ and recall that $\sin(\omega t) = \text{Im}(e^{j\omega t}) = \frac{e^{j\omega t} - e^{-j\omega t}}{2j}$
- ▶ By superposition, the steady-state response to $r(t) = \sin(\omega t)$ is:

$$\begin{aligned} y_{ss}(t) &= \frac{1}{2j} G(j\omega) e^{j\omega t} - \frac{1}{2j} G(j\omega) e^{-j\omega t} \\ &= |G(j\omega)| e^{j\angle G(j\omega)} \frac{e^{j\omega t} - e^{-j\omega t}}{2j} = |G(j\omega)| \sin(\omega t + \angle G(j\omega)) \end{aligned}$$

Frequency Response

- ▶ The **frequency response** is the steady-state output of a system with sinusoidal input
- ▶ The frequency response of a system with transfer function $T(s)$ to a reference signal $r(t) = \sin(\omega t)$ is a sinusoid, scaled by $|T(j\omega)|$ and phase-shifted by $\angle T(j\omega)$:

$$y_{ss}(t) = |T(j\omega)| \sin(\omega t + \angle T(j\omega))$$

- ▶ The experimental determination of the frequency response is often easily accomplished due to the ready availability of sinusoidal test signals for various frequency ranges

Frequency Domain Plots

- ▶ Plotting the magnitude and phase of $T(j\omega)$ provides insight into the analysis and design of linear control systems

- ▶ The following frequency-domain plots of the transfer function are used:
 - ▶ **Polar plot:** a plot of $\text{Im}(T(j\omega))$ versus $\text{Re}(T(j\omega))$ of a transfer function $T(j\omega)$ as ω varies from 0 to ∞
 - ▶ **Magnitude-phase plot:** a plot of the log-magnitude $20 \log_{10} |T(j\omega)|$ in decibels (dB) versus the phase $\angle T(j\omega)$ as ω varies from 0 to ∞
 - ▶ **Bode plot:** a plot of the log-magnitude $20 \log_{10} |T(j\omega)|$ in decibels (dB) and the phase $\angle T(j\omega)$ versus $\log_{10} \omega$ as ω varies from 0 to ∞

Log-scale Units

- ▶ **Bel:** a relative measurement unit of the log-ratio of measured power P to reference power P_0

$$\text{Log-power ratio} = \log_{10} \left(\frac{P}{P_0} \right) \text{ Bels}$$

- ▶ **Decibel:** ten Bels:

$$\text{Log-power ratio} = 10 \log_{10} \left(\frac{P}{P_0} \right) \text{ dB}$$

- ▶ The input-output power spectral density relationship for a linear time-invariant system with input $R(s)$, transfer function $T(s)$, and output $Y(s)$ is:

$$S_Y(\omega) = |T(j\omega)|^2 S_R(\omega)$$

- ▶ The log-power ratio at ω in dB is:

$$10 \log_{10} \left(\frac{S_Y(\omega)}{S_R(\omega)} \right) = 10 \log_{10} |T(j\omega)|^2 = 20 \log_{10} |T(j\omega)|$$

Log-scale Units

- ▶ **Bode plot:** the magnitude $20 \log_{10} |T(j\omega)|$ in dB and phase $\angle T(j\omega)$ in radians of a transfer function $T(s)$ are plotted versus $\log_{10} \omega$
- ▶ The intervals on a log scale are known as decades (base 10) or octaves (base 2):
 - ▶ The number of **decades** between ω_1 and ω_2 is $\log_{10} \frac{\omega_2}{\omega_1}$
 - ▶ The number of **octaves** between ω_1 and ω_2 is $\log_2 \frac{\omega_2}{\omega_1}$
 - ▶ There are $\log_2(10) \approx 3.32$ octaves in one decade
 - ▶ A slope of 20 dB/decade is the same as $\frac{20 \text{ dB/decade}}{\log_2(10) \text{ octave/decade}} \approx 6 \text{ dB/octave}$

Transfer Function in Bode Form

- ▶ **Transfer function in Bode form:** a transfer function with m_1 real zeros, m_2 complex conjugate zero pairs, n_0 poles at the origin, n_1 real poles, and n_2 complex conjugate pole pairs:

$$T(s) = \kappa \frac{\prod_{i=1}^{m_1} \left(\frac{s}{z_i} + 1 \right) \prod_{l=1}^{m_2} \left(\left(\frac{s}{\omega_{n_l}} \right)^2 + 2\zeta_l \left(\frac{s}{\omega_{n_l}} \right) + 1 \right)}{s^{n_0} \prod_{i=1}^{n_1} \left(\frac{s}{p_i} + 1 \right) \prod_{k=1}^{n_2} \left(\left(\frac{s}{\omega_{n_k}} \right)^2 + 2\zeta_k \left(\frac{s}{\omega_{n_k}} \right) + 1 \right)}$$

- ▶ The magnitude and phase of $T(j\omega)$ are needed to draw a Bode plot

Magnitude and Phase of $T(j\omega)$

- Magnitude of $T(j\omega)$ in decibels (dB):

$$\begin{aligned} & 20 \log |T(j\omega)| \\ &= 20 \log |\kappa| + \sum_{i=1}^{m_1} 20 \log \left| j \frac{\omega}{z_i} + 1 \right| + \sum_{l=1}^{m_2} 20 \log \left| \left(\frac{j\omega}{\omega_{n_l}} \right)^2 + 2\zeta_l \left(\frac{j\omega}{\omega_{n_l}} \right) + 1 \right| \\ & - 20 \log |(j\omega)^{n_0}| - \sum_{i=1}^{n_1} 20 \log \left| j \frac{\omega}{p_i} + 1 \right| - \sum_{k=1}^{n_2} 20 \log \left| \left(\frac{j\omega}{\omega_{n_k}} \right)^2 + 2\zeta_k \left(\frac{j\omega}{\omega_{n_k}} \right) + 1 \right| \end{aligned}$$

- Phase of $T(j\omega)$ in radians:

$$\begin{aligned} \angle T(j\omega) &= \angle \kappa + \sum_{i=1}^{m_1} \tan^{-1} \left(\frac{\omega}{z_i} \right) + \sum_{l=1}^{m_2} \tan^{-1} \left(\frac{2\zeta_l \omega_{n_l} \omega}{\omega_{n_l}^2 - \omega^2} \right) \\ & - n_0 \frac{\pi}{2} - \sum_{i=1}^{n_1} \tan^{-1} \left(\frac{\omega}{p_i} \right) - \sum_{k=1}^{n_2} \tan^{-1} \left(\frac{2\zeta_k \omega_{n_k} \omega}{\omega_{n_k}^2 - \omega^2} \right) \end{aligned}$$

Drawing Bode Plots

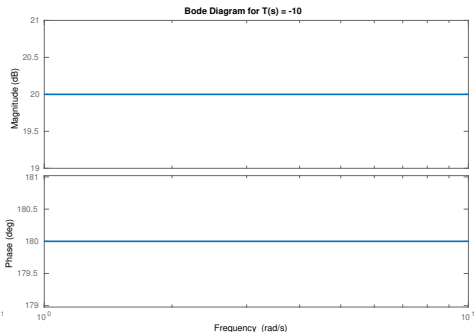
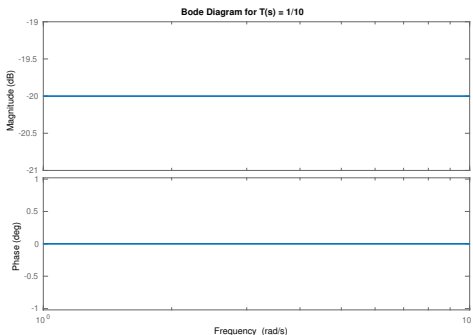
- ▶ Instead of computing the magnitude and phase of $T(j\omega)$ directly, it is preferable to obtain general rules for drawing Bode plots
- ▶ A transfer function may contain only four kinds of factors:
 - ▶ Constant terms: κ
 - ▶ Poles or zeros at the origin: s^q
 - ▶ Real poles or zeros: $\left(\frac{s}{p} + 1\right)^{-1}$ or $\left(\frac{s}{z} + 1\right)$
 - ▶ Complex conjugate poles or zeros: $\left(\left(\frac{s}{\omega_n}\right)^2 + 2\zeta\left(\frac{s}{\omega_n}\right) + 1\right)^{\pm 1}$
- ▶ If we determine the magnitude and phase plots for these four factors, then we can add them together graphically to obtain a Bode plot for any transfer function

Bode Plot for a Constant Term κ

► **Magnitude:** $20 \log |\kappa|$

► **Phase:** $\angle \kappa = \begin{cases} 0 & \text{if } \kappa > 0 \\ \pi & \text{if } \kappa < 0 \end{cases}$

► **Example:** Bode plot for $T(s) = \frac{1}{10}$ and $T(s) = -10$



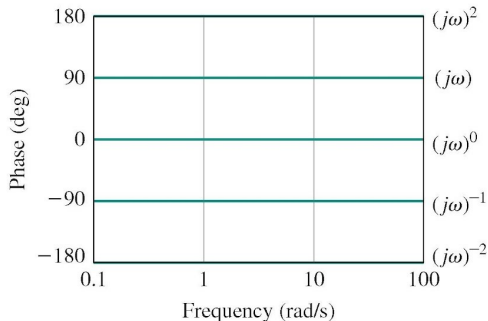
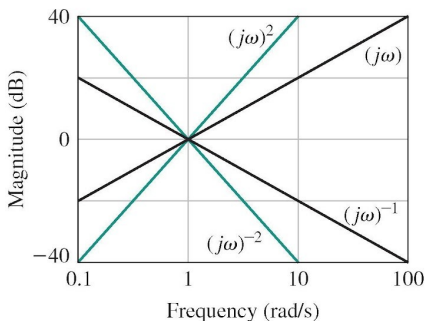
Bode Plot for Pole or Zero at the Origin: s^q

- **Magnitude:** a straight line on a log scale going through the origin with slope $20q$:

$$20 \log |(j\omega)^q| = 20q \log |\omega|$$

- **Phase:** a horizontal line at $q\frac{\pi}{2}$:

$$\angle (j\omega)^q = q \angle (j\omega) = q \frac{\pi}{2}$$



Bode Plot for Real Zero ($\frac{s}{z} + 1$)

► **Magnitude:** $20 \log \left| j\frac{\omega}{z} + 1 \right| = 20 \log \sqrt{1 + \left(\frac{\omega}{z}\right)^2}$

► **Phase:** $\angle \left(j\frac{\omega}{z} + 1 \right) = \tan^{-1} \frac{\omega}{z}$

► Extreme ω values:

► **Case 1:** $\omega \ll z$: horizontal line at 0:

$$20 \log \left| j\frac{\omega}{z} + 1 \right| \approx 0 \qquad \angle \left(j\frac{\omega}{z} + 1 \right) \approx 0$$

► **Case 2:** $\omega \gg z$: log-scale line of slope 20 going through 0 when $\omega = z$:

$$20 \log \left| j\frac{\omega}{z} + 1 \right| \approx 20 \log \frac{1}{z} + 20 \log \omega \qquad \angle \left(j\frac{\omega}{z} + 1 \right) \approx \frac{\pi}{2}$$

► **Case 3:** $\omega = z$ (**corner frequency**):

$$20 \log \left| j\frac{\omega}{z} + 1 \right| \approx 3dB \qquad \angle \left(j\frac{\omega}{z} + 1 \right) = \frac{\pi}{4}$$

Bode Plot for Real Pole $\left(\frac{s}{p} + 1\right)^{-1}$

► **Magnitude:** $20 \log \left| \left(j\frac{\omega}{p} + 1\right)^{-1} \right| = -20 \log \sqrt{1 + \left(\frac{\omega}{p}\right)^2}$

► **Phase:** $\angle \left(j\frac{\omega}{p} + 1\right)^{-1} = -\tan^{-1} \frac{\omega}{p}$

► Extreme ω values:

► **Case 1:** $\omega \ll p$: horizontal line at 0:

$$-20 \log \left| j\frac{\omega}{p} + 1 \right| \approx 0 \qquad \angle \left(j\frac{\omega}{p} + 1\right)^{-1} \approx 0$$

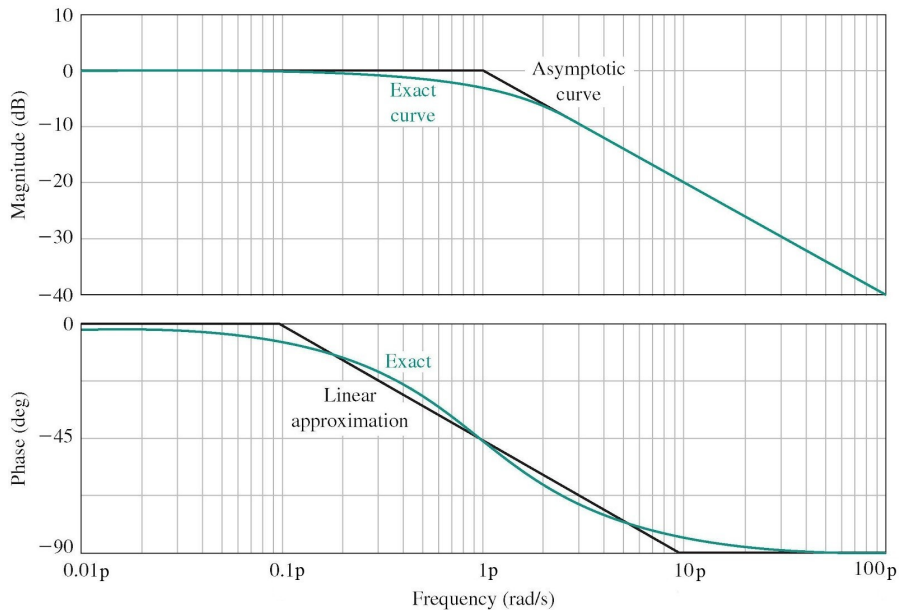
► **Case 2:** $\omega \gg p$: log-scale line of slope -20 going through 0 when $\omega = p$:

$$-20 \log \left| j\frac{\omega}{p} + 1 \right| \approx -20 \log \frac{1}{p} - 20 \log \omega \qquad \angle \left(j\frac{\omega}{p} + 1\right)^{-1} \approx -\frac{\pi}{2}$$

► **Case 3:** $\omega = p$ (**corner frequency**):

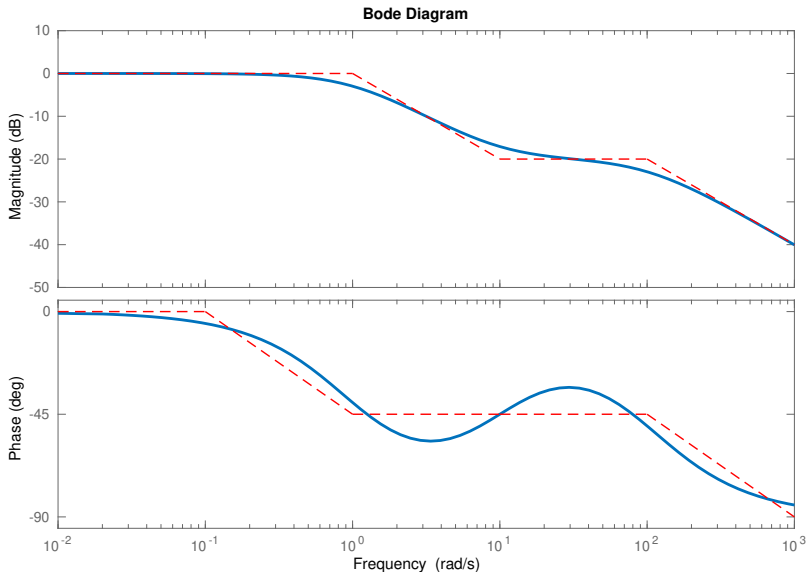
$$-20 \log \left| j\frac{\omega}{p} + 1 \right| \approx -3dB \qquad \angle \left(j\frac{\omega}{p} + 1\right)^{-1} \approx -\frac{\pi}{4}$$

Bode Plot for Real Pole $\left(\frac{s}{p} + 1\right)^{-1}$



Bode Plot Example 1

- Draw a Bode plot for $T(s) = 10 \frac{s+10}{(s+1)(s+100)} = \frac{(s/10+1)}{(s+1)(s/100+1)}$



Bode Plot for Complex Conjugate Zeros

▶ Consider $T(s) = \left(\left(\frac{s}{\omega_n} \right)^2 + 2\zeta \left(\frac{s}{\omega_n} \right) + 1 \right)$

▶ **Magnitude:**

$$|T(j\omega)| = \left| -\frac{\omega^2}{\omega_n^2} + 2\zeta \frac{\omega}{\omega_n} j + 1 \right| = \sqrt{\left(1 - \left(\frac{\omega}{\omega_n} \right)^2 \right)^2 + 4\zeta^2 \left(\frac{\omega}{\omega_n} \right)^2}$$

▶ **Phase:**

$$\angle T(j\omega) = \angle \frac{-\frac{\omega^2}{\omega_n^2} + 2\zeta \frac{\omega}{\omega_n} j + 1}{1} = \tan^{-1} \left(\frac{2\zeta \left(\frac{\omega}{\omega_n} \right)}{1 - \left(\frac{\omega}{\omega_n} \right)^2} \right)$$

Bode Plot for Complex Conjugate Zeros

$$|T(j\omega)| = \sqrt{\left(1 - \left(\frac{\omega}{\omega_n}\right)^2\right)^2 + 4\zeta^2 \left(\frac{\omega}{\omega_n}\right)^2} \quad \angle T(j\omega) = \tan^{-1} \left(\frac{2\zeta \left(\frac{\omega}{\omega_n}\right)}{1 - \left(\frac{\omega}{\omega_n}\right)^2} \right)$$

► Extreme ω values:

- **Case 1:** $\omega \ll \omega_n$: horizontal line at 0:

$$20 \log |T(j\omega)| \approx 0$$

$$\angle T(j\omega) \approx 0$$

- **Case 2:** $\omega \gg \omega_n$: log-scale line of slope 40 going through 0 when $\omega = \omega_n$:

$$20 \log |T(j\omega)| \approx 20 \log \sqrt{\left(\frac{\omega}{\omega_n}\right)^4} = 40 \log \omega - 40 \log \omega_n \quad \angle T(j\omega) \approx \pi$$

- **Case 3:** $\omega = \omega_n$:

$$20 \log |T(j\omega)| = 20 \log(2\zeta)$$

$$\angle T(j\omega) = \frac{\pi}{2}$$

Bode Plot for Complex Conjugate Poles

- Consider $T(s) = \left(\left(\frac{s}{\omega_n} \right)^2 + 2\zeta \left(\frac{s}{\omega_n} \right) + 1 \right)^{-1}$

$$|T(j\omega)| = \frac{1}{\sqrt{\left(1 - \left(\frac{\omega}{\omega_n}\right)^2\right)^2 + 4\zeta^2 \left(\frac{\omega}{\omega_n}\right)^2}} \quad \angle T(j\omega) = -\tan^{-1} \left(\frac{2\zeta \left(\frac{\omega}{\omega_n}\right)}{1 - \left(\frac{\omega}{\omega_n}\right)^2} \right)$$

- Extreme ω values:

- **Case 1:** $\omega \ll \omega_n$: horizontal line at 0:

$$20 \log |T(j\omega)| \approx 0 \quad \angle T(j\omega) \approx 0$$

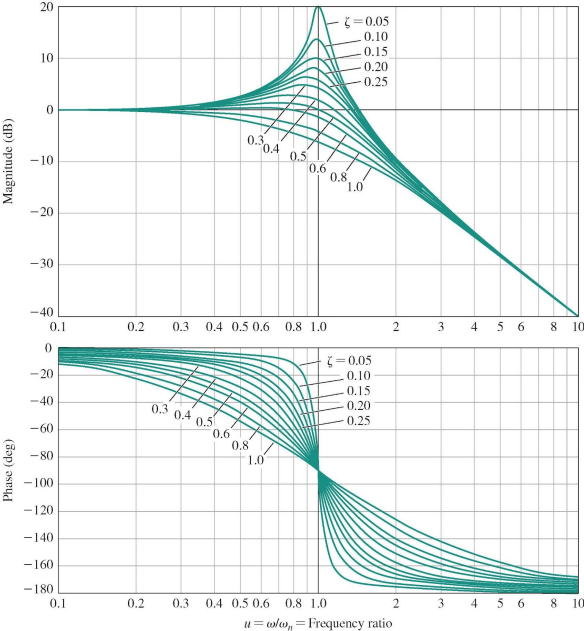
- **Case 2:** $\omega \gg \omega_n$: log-scale line of slope -40 going through 0 when $\omega = \omega_n$

$$20 \log |T(j\omega)| \approx -20 \log \sqrt{\left(\frac{\omega}{\omega_n}\right)^4} = -40 \log \omega + 40 \log \omega_n \quad \angle T(j\omega) \approx -\pi$$

- **Case 3:** $\omega = \omega_n$:

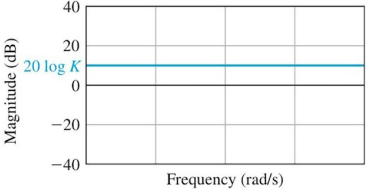
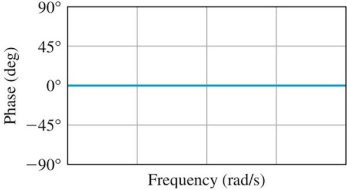
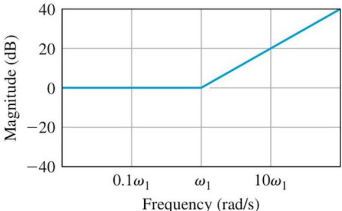
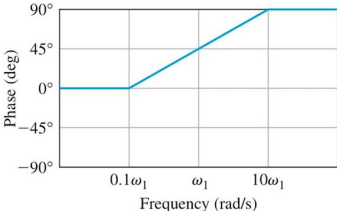
$$20 \log |T(j\omega)| = -20 \log(2\zeta) \quad \angle T(j\omega) = -\frac{\pi}{2}$$

Bode Plot for Complex Conjugate Poles



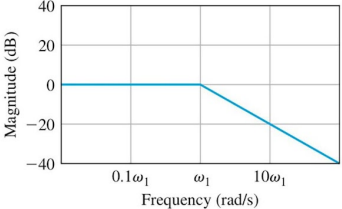
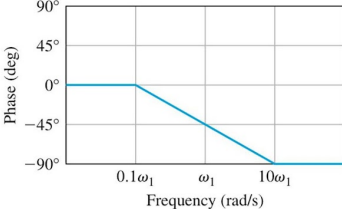
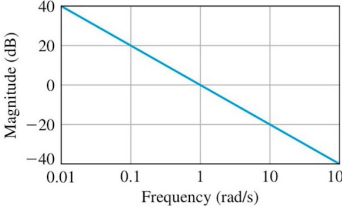
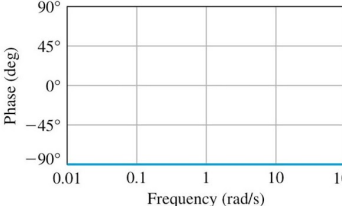
Bode Plot Approximations for Basic Transfer Function Terms

Table 8.1 Asymptotic Curves for Basic Terms of a Transfer Function

Term	Magnitude $20 \log_{10} G(j\omega) $	Phase $\phi(\omega)$
1. Gain, $G(j\omega) = K$		
2. Zero, $G(j\omega) = 1 + j\omega/\omega_1$		

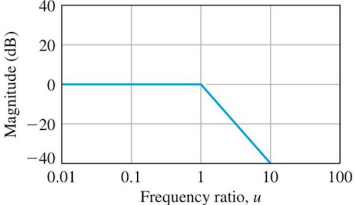
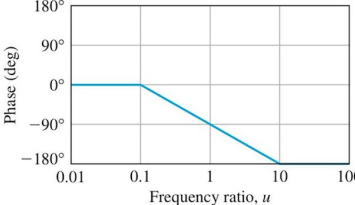
Bode Plot Approximations for Basic Transfer Function Terms

Table 8.1 Asymptotic Curves for Basic Terms of a Transfer Function

Term	Magnitude $20 \log_{10} G(j\omega) $	Phase $\phi(\omega)$
3. Pole, $G(j\omega) = (1 + j\omega/\omega_1)^{-1}$	 <p>Magnitude (dB)</p> <p>Frequency (rad/s)</p>	 <p>Phase (deg)</p> <p>Frequency (rad/s)</p>
4. Pole at the origin, $G(j\omega) = 1/j\omega$	 <p>Magnitude (dB)</p> <p>Frequency (rad/s)</p>	 <p>Phase (deg)</p> <p>Frequency (rad/s)</p>

Bode Plot Approximations for Basic Transfer Function Terms

Table 8.1 Asymptotic Curves for Basic Terms of a Transfer Function

Term	Magnitude $20 \log_{10} G(j\omega) $	Phase $\phi(\omega)$
5. Two complex poles, $0.1 < \zeta < 1$, $G(j\omega) = (1 + j2\zeta u - u^2)^{-1}$ $u = \omega/\omega_n$	 <p>Magnitude (dB)</p> <p>Frequency ratio, u</p>	 <p>Phase (deg)</p> <p>Frequency ratio, u</p>

Copyright ©2017 Pearson Education, All Rights Reserved

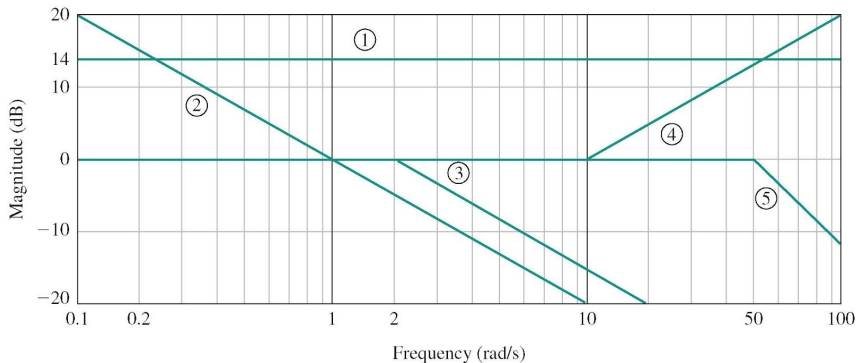
Bode Plot Example 2

- ▶ Draw a Bode plot for $T(s) = \frac{4(1+0.1s)}{s(1+0.5s)(1+0.6(s/50)+(s/50)^2)}$
- ▶ Factors in order of their occurrence as $s = j\omega$ increases:
 1. A constant gain $\kappa = 4$
 2. A pole at the origin
 3. A pole at $\omega = 2$
 4. A zero at $\omega = 10$
 5. A pair of complex poles at $\omega = \omega_n = 50$

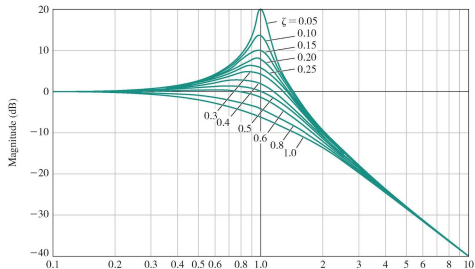
Bode Plot Example 2

- ▶ Consider the approximate magnitude plots:
 1. **Constant gain:** $20 \log |\kappa| = 14$ dB
 2. **Pole at the origin:** a line with slope -20 dB/decade going 0 when $\omega = 1$
 3. **Pole at $\omega = 2$:** horizontal line at 0 dB until the corner frequency at $\omega = 2$ and a line with slope -20 dB/decade after
 4. **Zero at $\omega = 10$:** horizontal line at 0 dB until the corner frequency at $\omega = 10$ and a line with slope 20 dB/decade after
 5. **Complex pole pair at $\omega = \omega_n = 50$:** horizontal line at 0 dB until the corner frequency at $\omega = 50$ and a line with slope -40 dB/decade after
- ▶ The approximations must be corrected at the corner frequencies:
 - ▶ Real zero/pole: ± 3 dB
 - ▶ Complex pair of zeros/poles: based on ζ

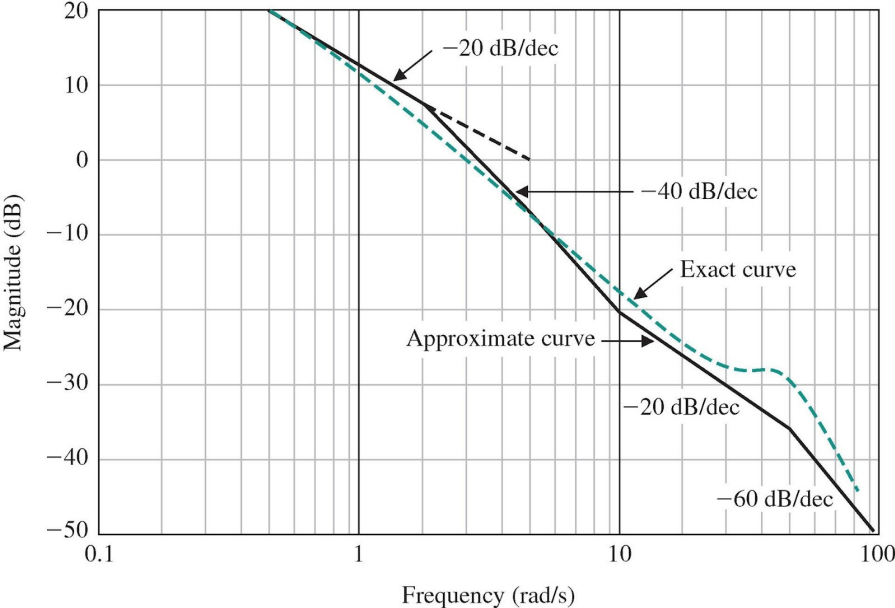
Bode Plot Example 2



► Complex pole pair correction:



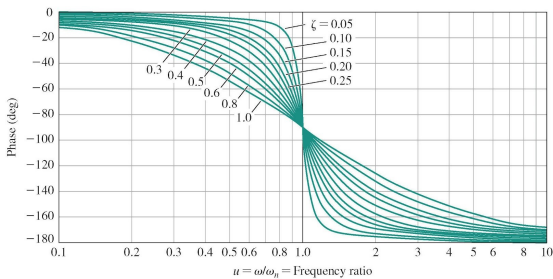
Bode Plot Example 2



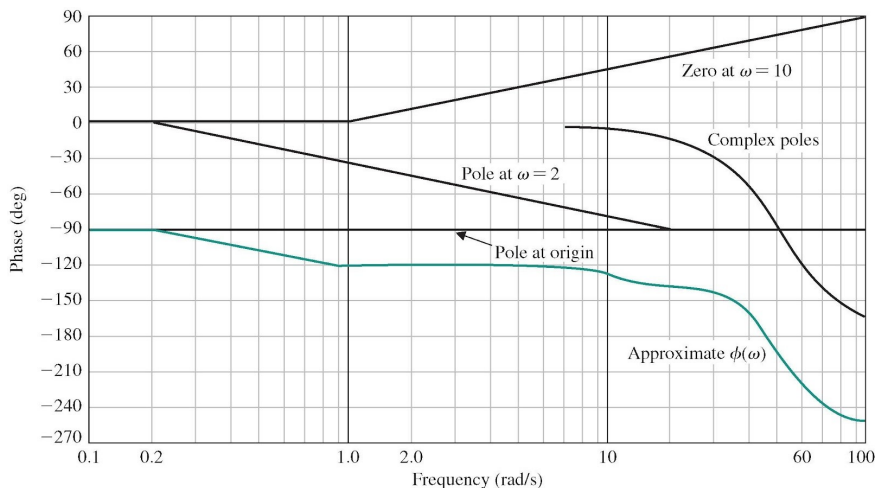
Bode Plot Example 2

- ▶ Consider the approximate phase plots:
 1. **Constant gain:** $\angle K = 0^\circ$
 2. **Pole at the origin:** -90°
 3. **Pole at $\omega = 2$:** a line with slope -45 deg/decade from $\omega = 0.2$ to $\omega = 20$
 4. **Zero at $\omega = 10$:** a line with slope 45 deg/decade from $\omega = 1$ to $\omega = 100$
 5. **Complex pole pair at $\omega = \omega_n = 50$:** phase shift of -90 deg/decade from $\omega = 5$ to $\omega = 500$

- ▶ The actual phase characteristic for the complex pole pair should be obtained from:



Bode Plot Example 2



- The exact phase shift can be evaluated at important frequencies:

$$\angle T(j\omega) = \angle K + \sum_{i=1}^{m_1} \tan^{-1} \left(\frac{\omega}{z_i} \right) + \sum_{l=1}^{m_2} \tan^{-1} \left(\frac{2\zeta_l \omega_{n_l} \omega}{\omega_{n_l}^2 - \omega^2} \right) - n_0 \frac{\pi}{2} - \sum_{i=1}^{n_1} \tan^{-1} \left(\frac{\omega}{p_i} \right) - \sum_{k=1}^{n_2} \tan^{-1} \left(\frac{2\zeta_k \omega_{n_k} \omega}{\omega_{n_k}^2 - \omega^2} \right)$$

Bode Plot Example 3

- ▶ Draw a Bode plot for

$$T(s) = \frac{(s+1)(s^2+3s+100)}{s^2(s+10)(s+100)} = \frac{(s+1)((s/10)^2 + 2(0.15)(s/10) + 1)}{10s^2(s/10+1)(s/100+1)}$$

- ▶ Magnitude and phase at $\omega = 0.1$:

$$20 \log |T(j\omega)| \approx 20 \text{ dB} \qquad \angle T(j\omega) \approx -\pi$$

- ▶ Magnitude slope in dB/decade:

ω	Zero at -1	Zeros with $\omega_n = 10$	Double pole at 0	Pole at -10	Pole at -100
0.1 - 1	0	0	-40	0	0
1 - 10	20	0	-40	0	0
10 - 100	20	40	-40	-20	0
100 - 1000	20	40	-40	-20	-20

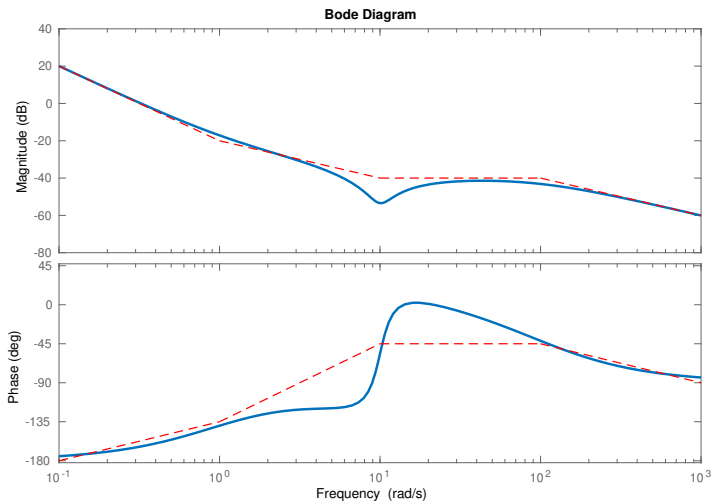
- ▶ Phase slope in degrees/decade:

ω	Zero at -1	Zeros with $\omega_n = 10$	Double pole at 0	Pole at -10	Pole at -100
0.1 - 1	45	0	0	0	0
1 - 10	45	90	0	-45	0
10 - 100	0	90	0	-45	-45
100 - 1000	0	0	0	0	-45

Bode Plot Example 3

- Draw a Bode plot for

$$T(s) = \frac{(s + 1)(s^2 + 3s + 100)}{s^2(s + 10)(s + 100)} = \frac{(s + 1)((s/10)^2 + 2(0.15)(s/10) + 1)}{10s^2(s/10 + 1)(s/100 + 1)}$$



Bode Plot Example 4

▶ Draw a Bode plot for $T(s) = \frac{4(s/2+1)}{s(1+2s)(1+0.05s+(s/8)^2)}$

▶ Magnitude at $\omega = 2^{-2}$:

$$20 \log |T(j\omega)| \approx 20 \log \left| \frac{4}{j\omega} \right| = 20 \log 16 \approx 24 \text{dB}$$

▶ Magnitude slope in dB/octave:

ω	Zero at -2	Pole at 0	Pole at -2^{-1}	Poles with $\omega_n = 2^3$
$2^{-2} - 2^{-1}$	0	-6	0	0
$2^{-1} - 2^1$	0	-6	-6	0
$2^1 - 2^3$	6	-6	-6	0
$2^3 - 2^4$	6	-6	-6	-12

▶ Phase slope in degrees/decade

ω	Zero at -2	Pole at 0	Pole at -2^{-1}	Poles with $\omega_n = 2^3$
0.2 - 0.8	45	0	-45	0
0.8 - 5	45	0	-45	-90
5 - 20	45	0	0	-90
20 - 80	0	0	0	-90

Bode Plot Example 4

- Draw a Bode plot for $T(s) = \frac{4(s/2+1)}{s(1+2s)(1+0.05s+(s/8)^2)}$

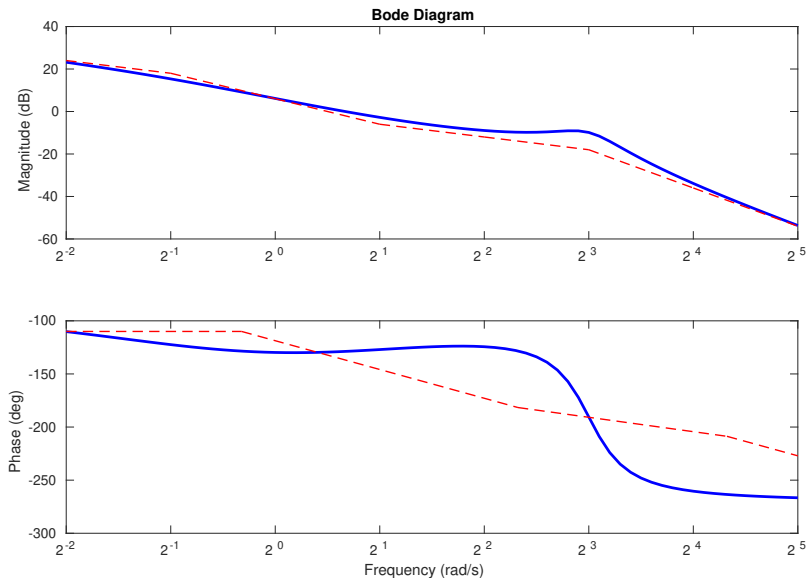
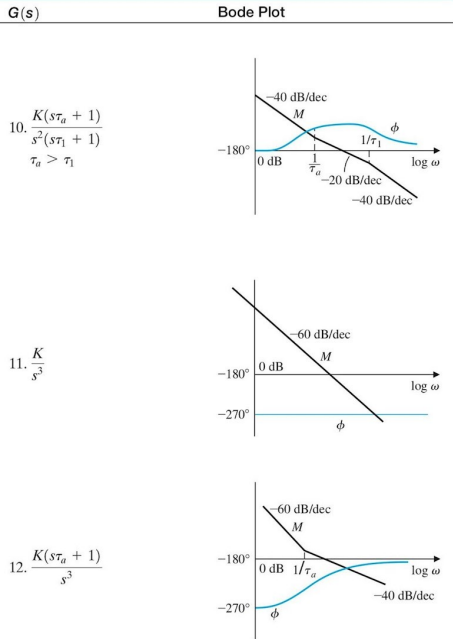
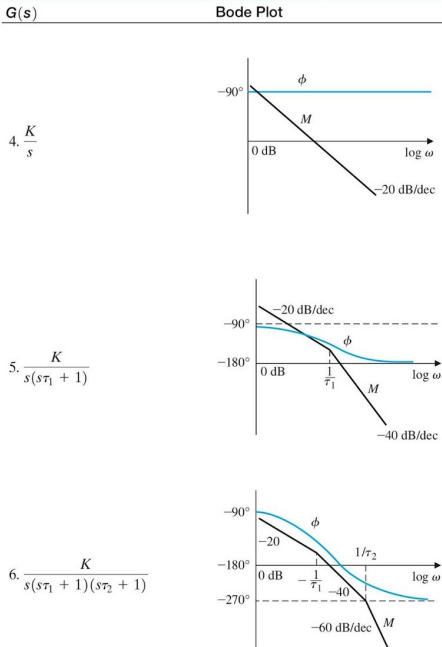


Table 8.2 Bode Plots for Typical Transfer Functions

$G(s)$	Bode Plot	$G(s)$	Bode Plot
1. $\frac{K}{s\tau_1 + 1}$		7. $\frac{K(s\tau_a + 1)}{s(s\tau_1 + 1)(s\tau_2 + 1)}$	
2. $\frac{K}{(s\tau_1 + 1)(s\tau_2 + 1)}$		8. $\frac{K}{s^2}$	
3. $\frac{K}{(s\tau_1 + 1)(s\tau_2 + 1)(s\tau_3 + 1)}$		9. $\frac{K}{s^2(s\tau_1 + 1)}$	

Table 8.2 Bode Plots for Typical Transfer Functions


Nonminimum Phase Systems

- ▶ **Minimum phase system:** a system whose transfer function poles and zeros are in the closed left half-plane
- ▶ **Nonminimum phase system:** a system whose transfer function has zeros in the right half-plane
- ▶ Bode plots can also be drawn for nonminimum phase systems
- ▶ The magnitude of a transfer function does not depend on whether the zeros are in the left or right half-plane
- ▶ The phase contribution of a zero in the right half-plane is always at least as large as the phase contribution of a zero in the left half-plane

Nonminimum Phase Systems

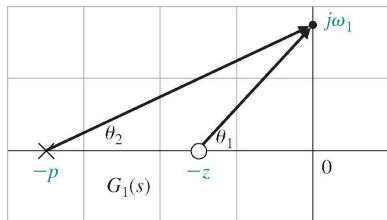
- ▶ To understand the difference between minimum and nonminimum phase systems compare the transfer functions:

$$G_1(s) = \frac{s + z}{s + p}$$

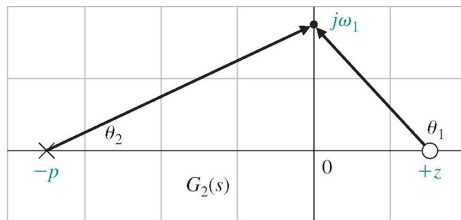
$$G_2(s) = \frac{s - z}{s + p}$$

- ▶ Magnitude: $|G_1(j\omega)| = |G_2(j\omega)| = \frac{\sqrt{\omega^2 + z^2}}{\sqrt{\omega^2 + p^2}}$

- ▶ Phase: $\angle G_1(j\omega_1)$ vs $\angle G_2(j\omega_1)$



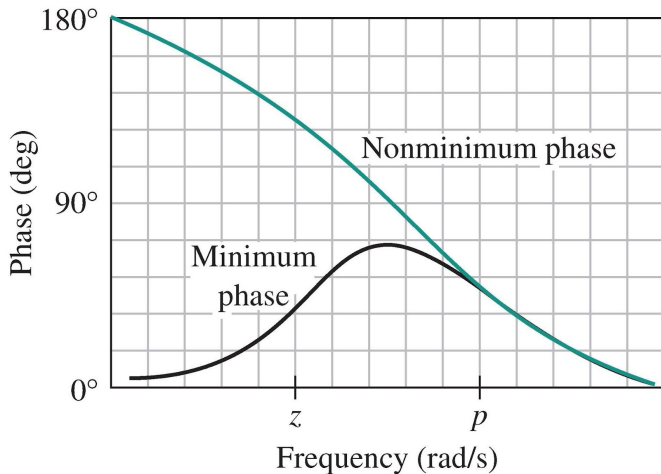
(a)



(b)

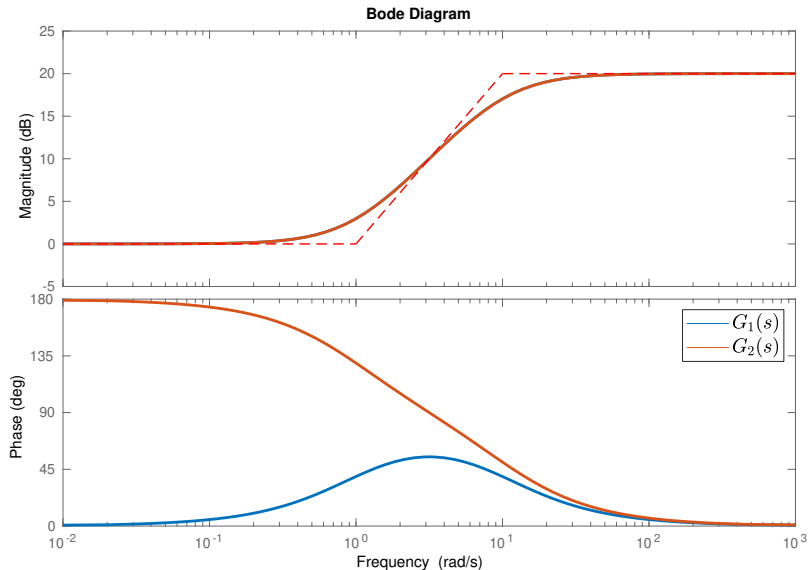
Nonminimum Phase Systems

- ▶ The range of phase shifts for a minimum phase transfer function is the least possible for a given magnitude curve



Nonminimum Phase Systems: Example

- ▶ Draw a Bode plot for $G_1(s) = 10 \frac{s+1}{s+10}$ and $G_2(s) = 10 \frac{s-1}{s+10}$

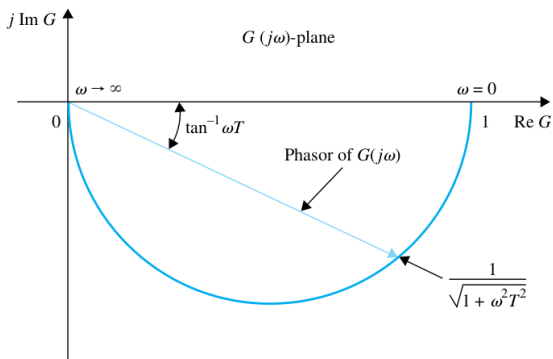


Polar Plot

- ▶ **Polar plot:** a plot of $\text{Im}(G(j\omega))$ versus $\text{Re}(G(j\omega))$ of a transfer function $G(j\omega)$ as ω varies from 0 to ∞
- ▶ A polar plot contains less information than a Bode plot because the frequency values ω are not captured
- ▶ The general shape of the polar plot can be determined from:
 - ▶ Magnitude $|G(j\omega)|$ and phase $\angle G(j\omega)$ at $\omega = 0$ and $\omega = \infty$
 - ▶ Intersection of the polar plot with the real and imaginary axes

Polar Plot: Type 0 System

- ▶ Draw a polar plot for $G(s) = \frac{1}{1+Ts}$
- ▶ Magnitude: $|G(j\omega)| = \frac{1}{\sqrt{1+\omega^2 T^2}}$
- ▶ Phase: $\angle G(j\omega) = -\tan^{-1}(\omega T)$
- ▶ Polar plot: $|G(j0)| = 1$, $\angle G(j0) = 0$; $|G(j\infty)| = 0$, $\angle G(j\infty) = -\frac{\pi}{2}$



Polar Plot: Type 0 System

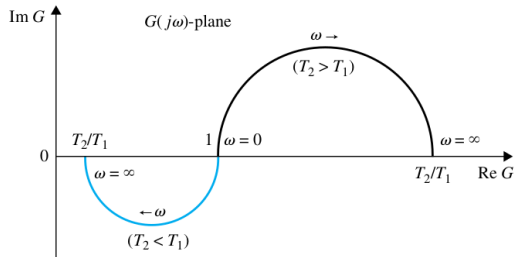
- ▶ Draw a polar plot for $G(s) = \frac{1+T_2s}{1+T_1s}$
- ▶ Magnitude: $|G(j\omega)| = \frac{\sqrt{1+\omega^2 T_2^2}}{\sqrt{1+\omega^2 T_1^2}}$
- ▶ Phase: $\angle G(j\omega) = \tan^{-1}(\omega T_2) - \tan^{-1}(\omega T_1)$
- ▶ The polar plot depends on the relative magnitudes of T_1 and T_2

- ▶ If $T_2 > T_1$:

$$|G(j\omega)| \geq 1 \quad \angle G(j\omega) \geq 0$$

- ▶ If $T_1 > T_2$:

$$|G(j\omega)| \leq 1 \quad \angle G(j\omega) \leq 0$$

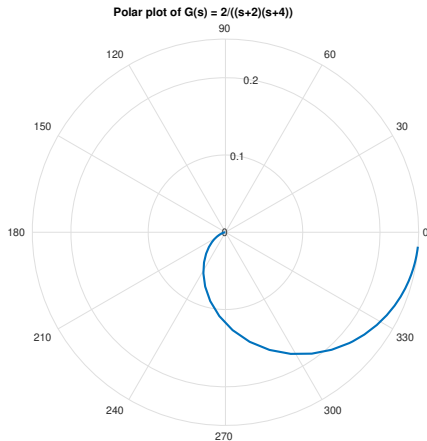


Polar Plot: Type 0 System

- ▶ Draw a polar plot for $G(s) = \frac{\kappa}{(1+T_1s)(1+T_2s)}$
- ▶ Magnitude $|G(j\omega)|$ and phase $\angle G(j\omega)$ at $\omega = 0$ and $\omega = \infty$:

$$G(j0) = \kappa \underline{0^\circ}$$

$$G(j\infty) = 0 \underline{-180^\circ}$$



Polar Plot: Type 1 System

► Draw a polar plot for $G(s) = \frac{\kappa}{s(1+\tau s)}$

► Magnitude $|G(j\omega)|$ and phase $\angle G(j\omega)$:

$$|G(j\omega)| = \frac{\kappa}{\sqrt{\omega^2 + \omega^4 \tau^2}}$$

$$\angle G(j\omega) = -\frac{\pi}{2} - \tan^{-1}(\omega\tau)$$

► Values at $\omega = 0$, $\omega = 1/\tau$, $\omega = \infty$:

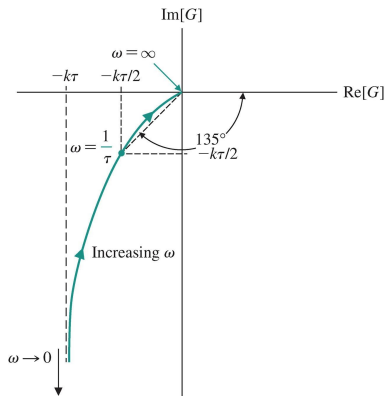
$$G(j0) = \infty \angle -90^\circ$$

$$G(j\frac{1}{\tau}) = \frac{\kappa\tau}{\sqrt{2}} \angle -135^\circ$$

$$G(j\infty) = 0 \angle -180^\circ$$

► Asymptote as $\omega \rightarrow 0$:

$$G(j\omega) = \frac{\kappa}{j\omega(1 + \tau j\omega)} \stackrel{\text{small } \omega}{\approx} \frac{\kappa}{j\omega} (1 - j\tau\omega) = -\kappa\tau - j\frac{\kappa}{\omega}$$



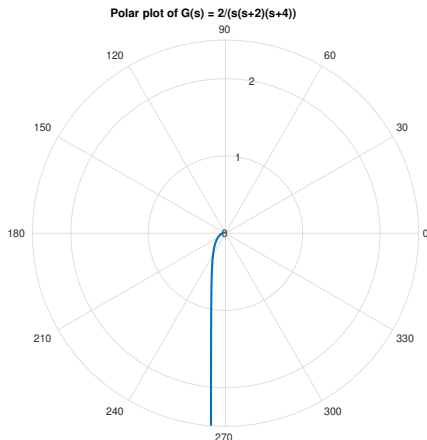
Copyright © 2017 Pearson Education, All Rights Reserved

Polar Plot: Type 1 System

- ▶ Draw a polar plot for $G(s) = \frac{K}{s(1+T_1s)(1+T_2s)}$
- ▶ Magnitude $|G(j\omega)|$ and phase $\angle G(j\omega)$ at $\omega = 0$ and $\omega = \infty$:

$$G(j0) = \infty \underline{\angle -90^\circ}$$

$$G(j\infty) = 0 \underline{\angle -270^\circ}$$

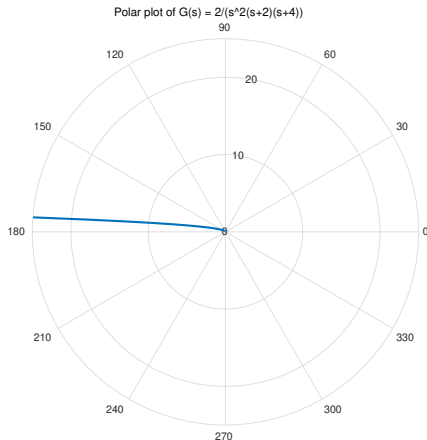


Polar Plot: Type 2 System

- ▶ Draw a polar plot for $G(s) = \frac{\kappa}{s^2(1+T_1s)(1+T_2s)}$
- ▶ Magnitude $|G(j\omega)|$ and phase $\angle G(j\omega)$ at $\omega = 0$ and $\omega = \infty$:

$$G(j0) = \infty \underline{\angle -180^\circ}$$

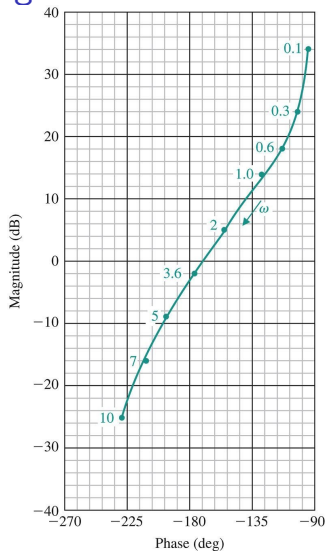
$$G(j\infty) = 0 \underline{\angle -360^\circ}$$



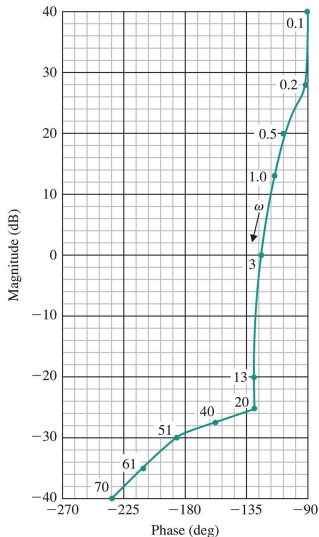
Magnitude-Phase Plot

- ▶ **Magnitude-phase plot:** a plot of the magnitude $20 \log_{10} |G(j\omega)|$ in decibels (dB) versus the phase $\angle G(j\omega)$ as ω varies from 0 to ∞
- ▶ A magnitude-phase plot can be obtained from the information on a Bode plot
- ▶ A magnitude-phase plot is shifted up or down when the gain factor κ varies
- ▶ The Bode plot property of adding plots of individual components does not carry over
- ▶ The magnitude-phase plot of the forward-path transfer function $G(s)$ of a unity-feedback system can be superposed on a Nichols chart to give information about the system's relative stability and frequency response

Magnitude-Phase Plot



Copyright ©2017 Pearson Education, All Rights Reserved



Copyright ©2017 Pearson Education, All Rights Reserved

$$(a) G_1(s) = \frac{5}{s(s/2+1)(s/6+2)}$$

$$(b) G_2(s) = \frac{5(s/10+1)}{s(s/2+1)(1+0.6(s/50)+(s/50)^2)}$$

Magnitude-Phase Plot

- ▶ The shape of the magnitude-phase plot is important where the magnitude approaches 0 dB and the phase approaches 180°
- ▶ **Gain-Crossover frequency:** ω at which $20 \log |G(j\omega)| = 0$ dB
- ▶ **Phase-Crossover frequency:** ω at which $\angle G(j\omega) = -\pi$
- ▶ Unity-feedback closed-loop transfer function:

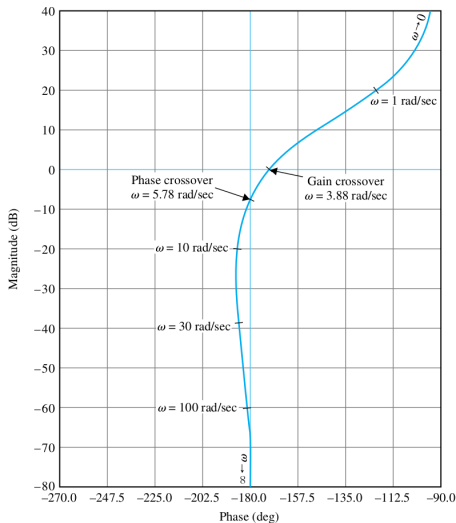
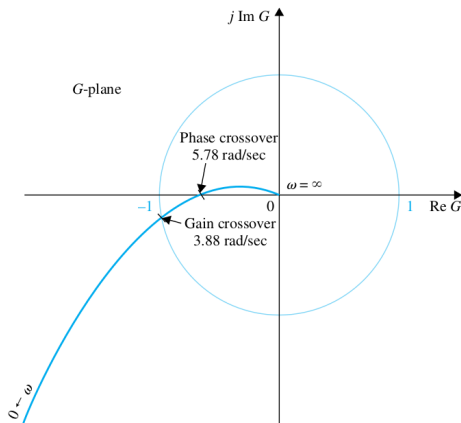
$$T(s) = \frac{G(s)}{1 + G(s)}$$

- ▶ Instability occurs when $1 + G(s) = 0$:

$$|G(s)| = 1 \qquad \angle G(s) = -\pi$$

Magnitude-Phase Plot

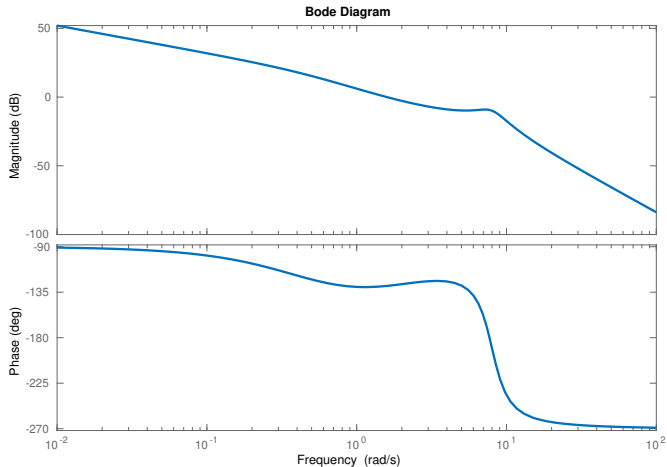
- Draw a polar plot and a magnitude-phase plot for $G(s) = \frac{10(s+10)}{s(s+2)(s+5)}$



Frequency Domain Plots in Matlab

► Bode plot for $G(s) = \frac{4(s/2+1)}{s(2s+1)(1+0.4(s/8)+(s/8)^2)}$

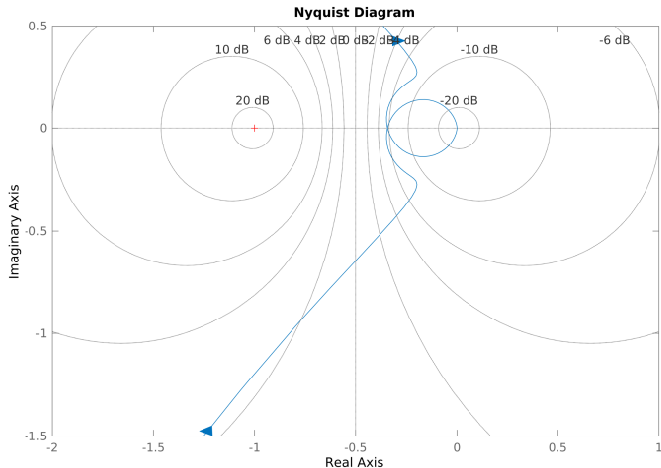
```
1  s = tf('s');  
2  G = 4*(s/2+1)/s/(1+2*s)/(1+0.4*(s/8) + (s/8)^2);  
3  bodeplot(G);
```



Frequency Domain Plots in Matlab

► Nyquist plot for $G(s) = \frac{4(s/2+1)}{s(2s+1)(1+0.4(s/8)+(s/8)^2)}$

```
1 s = tf('s');  
2 G = 4*(s/2+1)/s/(1+2*s)/(1+0.4*(s/8) + (s/8)^2);  
3 nyquistplot(G);
```



Frequency Domain Plots in Matlab

► Nichols plot for $G(s) = \frac{4(s/2+1)}{s(2s+1)(1+0.4(s/8)+(s/8)^2)}$

```
1  s = tf('s');  
2  G = 4*(s/2+1)/s/(1+2*s)/(1+0.4*(s/8) + (s/8)^2);  
3  nicholsplot(G);
```

