

# ECE276A: Sensing & Estimation in Robotics

## Lecture 2: Probability Theory (Review)

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# Events

- ▶ **Experiment:** any procedure that can be repeated infinitely and has a well-defined set of possible outcomes.
- ▶ **Sample space  $\Omega$ :** the set of possible outcomes of an experiment.
  - ▶  $\Omega = \{HH, HT, TH, TT\}$
  - ▶  $\Omega = \{\square, \square, \square, \square, \square, \square\}$
- ▶ **Event  $A$ :** a subset of the possible outcomes  $\Omega$ 
  - ▶  $A = \{HH\}$ ,  $B = \{HT, TH\}$
- ▶ **Probability of an event:**  $\mathbb{P}(A) = \frac{\text{"volume of } A\text{"}}{\text{"volume of } \Omega\text{"}}$

## Measure and Probability Space

- ▶  **$\sigma$ -algebra**: a collection of subsets of  $\Omega$  closed under complementation and countable unions.
- ▶ **Borel  $\sigma$ -algebra  $\mathcal{B}$** : the smallest  $\sigma$ -algebra containing all open sets from a topological space. Necessary because there is no valid translation invariant way to assign a finite measure to all subsets of  $[0, 1)$ .
- ▶ **Measurable space**: a tuple  $(\Omega, \mathcal{F})$ , where  $\Omega$  is a sample space and  $\mathcal{F}$  is a  $\sigma$ -algebra.
- ▶ **Measure**: a function  $\mu : \mathcal{F} \rightarrow \mathbb{R}$  satisfying  $\mu(A) \geq 0$  for all  $A \in \mathcal{F}$  and countable additivity  $\mu(\cup_i A_i) = \sum_i \mu(A_i)$  for disjoint  $A_i$ .
- ▶ **Probability measure**: a measure that satisfies  $\mu(\Omega) = 1$ .
- ▶ **Probability space**: a triple  $(\Omega, \mathcal{F}, \mathbb{P})$ , where  $\Omega$  is a sample space,  $\mathcal{F}$  is a  $\sigma$ -algebra, and  $\mathbb{P} : \mathcal{F} \rightarrow [0, 1]$  is a probability measure.

# Probability Axioms

## ▶ Probability Axioms:

- ▶  $\mathbb{P}(A) \geq 0$
- ▶  $\mathbb{P}(\Omega) = 1$
- ▶ If  $\{A_i\}$  are disjoint, i.e.,  $A_i \cap A_j = \emptyset, \forall i \neq j$ , then  $\mathbb{P}(\bigcup_i A_i) = \sum_i \mathbb{P}(A_i)$

## ▶ Corollary:

- ▶  $\mathbb{P}(\emptyset) = 0$
- ▶  $\max\{\mathbb{P}(A), \mathbb{P}(B)\} \leq \mathbb{P}(A \cup B) = \mathbb{P}(A) + \mathbb{P}(B) - \mathbb{P}(A \cap B) \leq \mathbb{P}(A) + \mathbb{P}(B)$
- ▶  $A \subseteq B \Rightarrow \mathbb{P}(A) \leq \mathbb{P}(B)$

## Events Example

- ▶ An experiment consists of randomly selecting one chip among ten chips marked 1, 2, 2, 3, 3, 3, 4, 4, 4, 4.
  - ▶ What is a reasonable sample space for this experiment?  $\Omega = \{1, 2, 3, 4\}$
  - ▶ What is the probability of observing a chip marked with an even number?

$$\mathbb{P}(\{2, 4\}) = \mathbb{P}(\{2\} \cup \{4\}) = \mathbb{P}(\{2\}) + \mathbb{P}(\{4\}) = \frac{6}{10}$$

- ▶ What is the probability of observing a chip marked with a prime number?

$$\mathbb{P}(\{2, 3\}) = \mathbb{P}(\{2\} \cup \{3\}) = \mathbb{P}(\{2\}) + \mathbb{P}(\{3\}) = \frac{5}{10}$$

## Set of Events

▶ **Conditional Probability:**  $\mathbb{P}(A \cap B) = \mathbb{P}(A | B)\mathbb{P}(B)$

▶ **Bayes Theorem:** assume  $\mathbb{P}(B) > 0$

$$\mathbb{P}(A | B) = \frac{\mathbb{P}(A \cap B)}{\mathbb{P}(B)} = \frac{\mathbb{P}(B | A)\mathbb{P}(A)}{\mathbb{P}(B)}$$

▶ **Total Probability:** If  $\{A_1, \dots, A_n\}$  is a partition of  $\Omega$ , i.e.,  $\Omega = \bigcup_i A_i$  and  $A_i \cap A_j = \emptyset, \forall i \neq j$ , then:

$$\mathbb{P}(B) = \sum_{i=1}^n \mathbb{P}(B \cap A_i)$$

▶ **Corollary:** If  $\{A_1, \dots, A_n\}$  is a partition of  $\Omega$ , then:

$$\mathbb{P}(A_i | B) = \frac{\mathbb{P}(B | A_i)\mathbb{P}(A_i)}{\sum_{j=1}^n \mathbb{P}(B | A_j)\mathbb{P}(A_j)}$$

▶ **Independent events:**  $\mathbb{P}(\bigcap_i A_i) = \prod_i \mathbb{P}(A_i)$

- ▶ observing one does not give any information about another
- ▶ in contrast, disjoint events never occur together: one occurring tells you that others will not occur and hence, disjoint events are always dependent

## Independent Events Example

- ▶ A box contains 7 green and 3 red chips.
- ▶ Experiment: select one chip, replace the drawn chip, and repeat until the color red has been observed four times
- ▶ Assuming that no draw affects or is affected by any other draw, what is the probability that the experiment terminates on the ninth draw?

## Independent Events Example

- ▶ Let the sample space  $\Omega$  be a countably infinite set of all ordered tuples with elements from  $\{r, g\}$ :

$$\Omega = \{(r), (g), (r, r), (r, g), (g, r), (g, g), (r, r, r), \dots\}$$

- ▶ Let  $E \subset \Omega$  be such that:
  - ▶ Each tuple  $e \in E$  has 9 components  $e_1, \dots, e_9$
  - ▶ The last component  $e_9$  of each tuple  $e \in E$  is  $r$
  - ▶ There are exactly four components of  $r$  in each tuple  $e \in E$

$$\text{Example: } (g, r, g, r, g, r, g, g, r) \in E$$

- ▶ Idea:
  - ▶ Show that every singleton subset  $\{e\}$  of  $E$  has the same probability  $p_e$
  - ▶ Determine the cardinality of  $E$  so that  $\mathbb{P}(E) = \sum_{e \in E} \mathbb{P}(e) = |E|p_e$

- ▶ Due to independence, for any element  $e \in E$  we have:

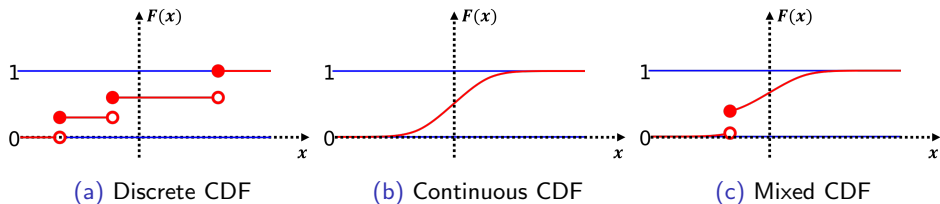
$$\mathbb{P}(\{e\}) = \mathbb{P}(\{e_1\} \cap \{e_2\} \cap \dots \cap \{e_9\}) = \prod_{i=1}^9 \mathbb{P}(\{e_i\}) = \left(\frac{3}{10}\right)^4 \left(\frac{7}{10}\right)^5$$

- ▶ Since  $e_9 = r$  for all  $e \in E$ , the cardinality of  $E$  is the number of ways to distribute 3 red chips among 8 slots, i.e.,  $|E| = \binom{8}{3}$



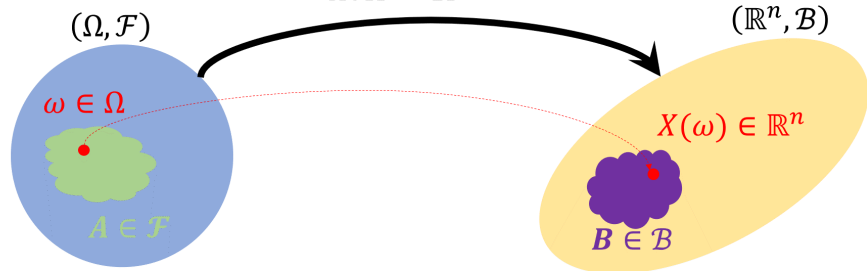
# Random Variable

- ▶ **Random variable**  $X$ : an  $\mathcal{F}$ -measurable function from  $(\Omega, \mathcal{F})$  to  $(\mathbb{R}, \mathcal{B})$ , i.e., a function  $X : \Omega \rightarrow \mathbb{R}$  s.t. the preimage of every set in  $\mathcal{B}$  is in  $\mathcal{F}$ .
- ▶ The **cumulative distribution function** (CDF)  $F(x) := \mathbb{P}(X \leq x)$  of a random variable  $X$  is non-decreasing, right-continuous, and  $\lim_{x \rightarrow \infty} F(x) = 1$  and  $\lim_{x \rightarrow -\infty} F(x) = 0$ .



# Random Variable

$$X: \Omega \mapsto \mathbb{R}^n$$



$$\mathbb{P}: \mathcal{F} \mapsto \mathbb{R}$$

$$\mathbb{P}(X \in B) = \mathbb{P}(A = \{\omega \in \Omega \mid X(\omega) \in B\})$$

*"Volume of the preimage of B under X"*

$$F_X(b) = \mathbb{P}(X \leq b) = \mathbb{P}(\{\omega \in \Omega \mid X(\omega) \in (-\infty, b_1] \times \cdots \times (-\infty, b_n]\})$$

$$= \int_{-\infty}^{b_n} \cdots \int_{-\infty}^{b_1} p_X(x_1, \dots, x_n) dx_1 \dots dx_n$$

## CDF Examples

- ▶  $X \sim \mathcal{U}([a, b])$

$$F(x) = \begin{cases} 0 & x < a \\ \frac{x-a}{b-a} & a \leq x \leq b \\ 1 & x > b \end{cases}$$

- ▶  $X \sim \mathcal{U}(\{a, b\})$

$$F(x) = \begin{cases} 0 & x < a \\ 1/2 & a \leq x < b \\ 1 & x \geq b \end{cases}$$

- ▶  $X \sim \text{Exp}(\lambda)$  with  $\lambda > 0$

$$F(x) = \begin{cases} 0 & x < 0 \\ 1 - e^{-\lambda x} & x \geq 0 \end{cases}$$

- ▶  $X \sim \mathcal{N}(\mu, \sigma^2)$

$$F(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \int_{-\infty}^x \exp\left(-\frac{1}{2} \frac{(y - \mu)^2}{\sigma^2}\right) dy$$

# Probability Mass Function

- ▶ The **probability mass function** (pmf)  $p(i)$  of a discrete random variable  $X : (\Omega, \mathcal{F}) \rightarrow (\mathbb{Z}, 2^{\mathbb{Z}})$  satisfies:
  - ▶  $p(i) \geq 0$
  - ▶  $\sum_{i \in \mathbb{Z}} p(i) = 1$
  - ▶  $F(i) = \mathbb{P}(X \leq i) = \sum_{j \leq i} p(j)$
  - ▶  $\mathbb{P}(X = i) = p(i) \in [0, 1]$
  - ▶  $\mathbb{P}(a < X \leq b) = F(b) - F(a) = \sum_{a < j \leq b} p(j)$

# Probability Density Function

- ▶ The **probability density function** (pdf)  $p(x)$  of a continuous random variable  $X : (\Omega, \mathcal{F}) \rightarrow (\mathbb{R}, \mathcal{B})$  satisfies:

- ▶  $p(x) \geq 0$

- ▶  $\int p(y)dy = 1$

- ▶  $F(x) = \mathbb{P}(X \leq x) = \int_{-\infty}^x p(y)dy$

- ▶  $\mathbb{P}(X = x) = \lim_{\epsilon \rightarrow 0} \int_x^{x+\epsilon} p(y)dy = 0$

- ▶  $\mathbb{P}(a < X \leq b) = F(b) - F(a) = \int_a^b p(y)dy$

- ▶ Intuition:

- ▶ The pdf  $p(x)$  of  $X$  behaves like a derivative of the CDF  $F(x)$

- ▶ The values  $p(a)$ ,  $p(b)$  measure the relative likelihood of  $X$  being  $a$  or  $b$

- ▶ A discrete random variable  $X \in \mathbb{Z}$  with pmf  $m(i)$  can be viewed as continuous by defining its pdf as  $p(x) := \sum_{i \in \mathbb{Z}} m(i)\delta(x - i)$ , where  $\delta$  is the Dirac delta function:

$$\delta(x) := \begin{cases} \infty & x = 0 \\ 0 & x \neq 0 \end{cases} \quad \int_{-\infty}^{\infty} \delta(x)dx = 1$$

## pmf/pdf Examples

- ▶  $X \sim \mathcal{U}([a, b])$

$$p(x) = \begin{cases} 0 & x < a \\ \frac{1}{b-a} & a \leq x \leq b \\ 0 & x > b \end{cases}$$

- ▶  $X \sim \mathcal{U}(\{a, b\})$

$$p(i) = \begin{cases} \frac{1}{2} & i \in \{a, b\} \\ 0 & \text{else} \end{cases}$$

- ▶  $X \sim \text{Exp}(\lambda)$  with  $\lambda > 0$

$$p(x) = \begin{cases} 0 & x < 0 \\ \lambda e^{-\lambda x} & x \geq 0 \end{cases}$$

- ▶  $X \sim \mathcal{N}(\mu, \sigma^2)$

$$p(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{1}{2} \frac{(x - \mu)^2}{\sigma^2}\right)$$

## Expectation and Variance

- ▶ Given a random variable  $X$  with pdf  $p$  and a measurable function  $g$ , the **expectation** of  $g(X)$  is:

$$\mathbb{E}[g(X)] = \int g(x)p(x)dx$$

- ▶ The **variance** of  $g(X)$  is:

$$\begin{aligned} \text{Var}[g(X)] &= \mathbb{E} \left[ (g(X) - \mathbb{E}[g(X)])(g(X) - \mathbb{E}[g(X)])^\top \right] \\ &= \mathbb{E} \left[ g(X)g(X)^\top \right] - \mathbb{E}[g(X)]\mathbb{E}[g(X)]^\top \end{aligned}$$

- ▶ The **variance** of a sum of random variables is:

$$\text{Var} \left[ \sum_{i=1}^n X_i \right] = \sum_{i=1}^n \text{Var}[X_i] + \sum_{i=1}^n \sum_{j \neq i} \text{Cov}[X_i, X_j]$$

$$\text{Cov}[X_i, X_j] = \mathbb{E} \left[ (X_i - \mathbb{E}[X_i])(X_j - \mathbb{E}[X_j])^\top \right] = \mathbb{E} \left[ X_i X_j^\top \right] - \mathbb{E}[X_i]\mathbb{E}[X_j]^\top$$

## Expectation and Variance Examples

- ▶  $X \sim \mathcal{U}([a, b])$

$$\mathbb{E}[X] = \int yp(y)dy = \frac{1}{b-a} \int_a^b ydy = \frac{b^2 - a^2}{2(b-a)} = \frac{1}{2}(a+b)$$

$$\text{Var}[X] = \int y^2 p(y)dy - \mathbb{E}[X]^2 = \frac{b^3 - a^3}{3(b-a)} - \frac{1}{4}(a+b)^2 = \frac{1}{12}(b-a)^2$$

- ▶  $X \sim \mathcal{U}(\{a, b\})$

$$\mathbb{E}[X] = \sum_{i \in \{a, b\}} i p(i) = \frac{1}{2}(a+b)$$

$$\text{Var}[X] = \mathbb{E}[X^2] - \mathbb{E}[X]^2 = \frac{1}{2}(a^2 + b^2) - \frac{1}{4}(a+b)^2 = \frac{1}{4}(b-a)^2$$



## Expectation and Variance Examples

- $X \sim \text{Exp}(\lambda)$  with  $\lambda > 0$

$$\begin{aligned}\mathbb{E}[X] &= \int_0^{\infty} y \lambda e^{-\lambda y} dy \stackrel{z=\lambda y, dz=\lambda dy}{=} \frac{1}{\lambda} \int_0^{\infty} z e^{-z} dz \\ &\stackrel{\substack{u=z, dv=e^{-z} dz \\ du=dz, v=-e^{-z}}}{=} \frac{1}{\lambda} \left( (-ze^{-z}) \Big|_0^{\infty} + \int_0^{\infty} e^{-z} dz \right) = \frac{1}{\lambda} (0 + 1) = \frac{1}{\lambda}\end{aligned}$$

$$\begin{aligned}\text{Var}[X] &= \int_0^{\infty} y^2 \lambda e^{-\lambda y} dy - \frac{1}{\lambda^2} \stackrel{z=\lambda y, dz=\lambda dy}{=} \frac{1}{\lambda^2} \left( \int_0^{\infty} z^2 e^{-z} dz - 1 \right) \\ &\stackrel{\substack{u=z^2, dv=e^{-z} dz \\ du=2z dz, v=-e^{-z}}}{=} \frac{1}{\lambda^2} \left( (-z^2 e^{-z}) \Big|_0^{\infty} + 2 \int_0^{\infty} z e^{-z} dz - 1 \right) = \frac{1}{\lambda^2}\end{aligned}$$

- $X \sim \mathcal{N}(\mu, \sigma^2)$

$$\begin{aligned}\mathbb{E}[X - \mu] &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \frac{(y - \mu)}{\sigma} \exp\left(-\frac{1}{2} \frac{(y - \mu)^2}{\sigma^2}\right) dy \\ &\stackrel{\substack{z=\frac{(y-\mu)^2}{2\sigma} \\ dz=\frac{(y-\mu)}{\sigma} dy}}{=} \frac{1}{\sqrt{2\pi}} \left( \int_{\infty}^{\mu^2/2\sigma} e^{-z/\sigma} dz + \int_{\mu^2/2\sigma}^{\infty} e^{-z/\sigma} dz \right) = 0\end{aligned}$$

## Set of Random Variables

- ▶ The **joint distribution** of random variables  $\{X_i\}_{i=1}^n$  on  $(\Omega, \mathcal{F}, \mathbb{P})$  defines their simultaneous behavior and is associated with a cumulative distribution function  $F(x_1, \dots, x_n) := \mathbb{P}(X_1 \leq x_1, \dots, X_n \leq x_n)$
- ▶ The CDF  $F_i(x_i)$  of  $X_i$  defines its **marginal distribution**
- ▶ The **joint probability density function**  $p(x_1, \dots, x_n)$  of  $n$  jointly absolutely continuous random variables  $X_i : (\Omega, \mathcal{F}) \rightarrow (\mathbb{R}, \mathcal{B})$  for  $i = 1, \dots, n$  satisfies:
  - ▶  $p(x_1, \dots, x_n) \geq 0$
  - ▶  $\int \cdots \int p(y_1, \dots, y_n) dy_1 \cdots dy_n = 1$
  - ▶ 
$$F(x_1, \dots, x_n) = \mathbb{P}(X_1 \leq x_1, \dots, X_n \leq x_n) \\ = \int_{-\infty}^{x_n} \cdots \int_{-\infty}^{x_1} p(y_1, \dots, y_n) dy_1 \cdots dy_n$$

# Gaussian Distribution

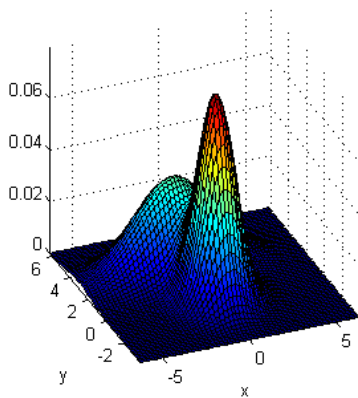
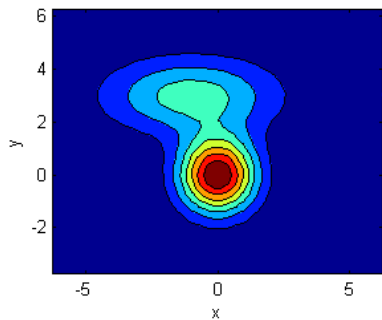
## ▶ Gaussian random vector $X \sim \mathcal{N}(\boldsymbol{\mu}, \Sigma)$

- ▶ parameters: **mean**  $\boldsymbol{\mu} \in \mathbb{R}^n$ , **covariance**  $\Sigma \in \mathbb{S}_{>0}^n$  (symmetric positive definite  $n \times n$  matrix)
- ▶ pdf:  $\phi(\mathbf{x}; \boldsymbol{\mu}, \Sigma) := \frac{1}{\sqrt{(2\pi)^n \det(\Sigma)}} \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^\top \Sigma^{-1}(\mathbf{x} - \boldsymbol{\mu})\right)$
- ▶ expectation:  $\mathbb{E}[X] = \int \mathbf{x}\phi(\mathbf{x}; \boldsymbol{\mu}, \Sigma)d\mathbf{x} = \boldsymbol{\mu}$
- ▶ variance:  $\text{Var}[X] = \mathbb{E}\left[(X - \mathbb{E}[X])(X - \mathbb{E}[X])^\top\right] = \Sigma$

## ▶ Gaussian mixture $X \sim \mathcal{NM}(\{\alpha_k\}, \{\boldsymbol{\mu}_k\}, \{\Sigma_k\})$

- ▶ parameters: **weights**  $\alpha_k \geq 0$ ,  $\sum_k \alpha_k = 1$ ,  
**means**  $\boldsymbol{\mu}_k \in \mathbb{R}^n$ , **covariances**  $\Sigma_k \in \mathbb{S}_{\geq 0}^n$
- ▶ pdf:  $p(\mathbf{x}) := \sum_k \alpha_k \phi(\mathbf{x}; \boldsymbol{\mu}_k, \Sigma_k)$
- ▶ expectation:  $\mathbb{E}[X] = \int \mathbf{x}p(\mathbf{x})d\mathbf{x} = \sum_k \alpha_k \boldsymbol{\mu}_k =: \bar{\boldsymbol{\mu}}$
- ▶ variance:  $\text{Var}[X] = \mathbb{E}[XX^\top] - \mathbb{E}[X]\mathbb{E}[X]^\top = \sum_k \alpha_k (\Sigma_k + \boldsymbol{\mu}_k \boldsymbol{\mu}_k^\top) - \bar{\boldsymbol{\mu}} \bar{\boldsymbol{\mu}}^\top$

## pdf of a Mixture of Two 2-D Gaussians



## Independent Random Variables

- ▶ The random variables  $\{X_i\}_{i=1}^n$  with joint CDF  $F(x_1, \dots, x_n)$  and marginal CDFs  $\{F_i(x_i)\}_{i=1}^n$  are **jointly independent** iff:

$$F(x_1, \dots, x_n) = \prod_{i=1}^n F_i(x_i), \quad \text{for all } x_1, \dots, x_n \in \mathbb{R}.$$

- ▶ The random variables  $\{X_i\}_{i=1}^n$  with joint pdf/pmf  $p(x_1, \dots, x_n)$  and marginal pdfs/pmfs  $\{p_i(x_i)\}_{i=1}^n$  are **jointly independent** iff:

$$p(x_1, \dots, x_n) = \prod_{i=1}^n p_i(x_i), \quad \text{for all } x_1, \dots, x_n \in \mathbb{R}.$$

- ▶ Let  $X$  and  $Y$  be random variables and suppose  $\mathbb{E}[X]$ ,  $\mathbb{E}[Y]$ , and  $\mathbb{E}[XY]$  exist. Then,  $X$  and  $Y$  are **uncorrelated** iff  $\mathbb{E}[XY] = \mathbb{E}[X]\mathbb{E}[Y]$  or equivalently  $\text{Cov}[X, Y] = 0$ .
- ▶ Independence implies uncorrelatedness

## Conditional and Total Probability

- ▶ **Total Probability:** If two random variables  $X, Y$  have a joint pdf  $p(x, y)$ , the marginal pdf  $p(x)$  of  $X$  is:

$$p(x) = \int p(x, y) dy$$

- ▶ **Conditional Distribution:** If two random variables  $X, Y$  have a joint pdf  $p(x, y)$ , the pdf  $p(x|y)$  of  $X$  conditioned on  $Y = y$  and the pdf  $p(y|x)$  of  $Y$  conditioned on  $X = x$  satisfy

$$p(x, y) = p(x|y)p(y) = p(y|x)p(x)$$

- ▶ **Bayes Theorem:** The pdf  $p(x|y)$  of  $X$  conditioned on  $Y = y$  can be expressed in terms of the pdf  $p(y|x)$  of  $Y$  conditioned on  $X = x$  and the marginal pdf  $p(x)$  of  $X$ :

$$p(x|y) = \frac{p(y|x)p(x)}{p(y)} = \frac{p(y|x)p(x)}{\int p(y | x')p(x')dx'}$$

## Joint and Marginal Distribution Example

- ▶ Suppose  $V = (X, Y)$  is a continuous random vector with density  $p_V(x, y) = 8xy$  for  $0 < y < x$  and  $0 < x < 1$
- ▶ Let  $g(x, y) := 2x + y$ 
  - ▶ Determine  $\mathbb{E}[g(V)]$
  - ▶ Evaluate  $\mathbb{E}[X]$  and  $\mathbb{E}[Y]$  by finding the marginal densities of  $X$  and  $Y$  and then evaluating the appropriate univariate integrals
  - ▶ Determine  $\text{Var}[g(V)]$

## Joint and Marginal Distribution Example

$$\mathbb{E}[2X + Y] = \int_0^1 \int_0^x (2x + y)8xy \, dydx = \frac{32}{15}$$

$$p_X(x) = \int_0^x 8xy \, dy = 4x^3 \text{ for } 0 \leq x \leq 1$$

$$\mathbb{E}[X] = \int_0^1 xp_X(x)dx = \int_0^1 4x^4 dx = \frac{4}{5}$$

$$p_Y(y) = \int_y^1 8xy \, dx = 4y - 4y^3 \text{ for } 0 \leq y \leq 1$$

$$\mathbb{E}[Y] = \int_0^1 yp_Y(y)dy = \int_0^1 4y^2 - 4y^4 dy = \frac{8}{15}$$

$$\begin{aligned} \text{Var}[g(V)] &= \mathbb{E}[(g(V) - \mathbb{E}[g(V)])^2] = \mathbb{E}\left[\left(2X + Y - \frac{32}{15}\right)^2\right] \\ &= \int_0^1 \int_0^x \left(2x + y - \frac{32}{15}\right)^2 8xy \, dydx = \frac{17}{75} \end{aligned}$$



## Conditional Probability Example

- ▶ Suppose that  $V = (X, Y)$  is a discrete random vector with probability mass function:

$$p_V(x, y) = \begin{cases} 0.10 & \text{if } (x, y) = (0, 0) \\ 0.20 & \text{if } (x, y) = (0, 1) \\ 0.30 & \text{if } (x, y) = (1, 0) \\ 0.15 & \text{if } (x, y) = (1, 1) \\ 0.25 & \text{if } (x, y) = (2, 2) \\ 0 & \text{elsewhere} \end{cases}$$

- ▶ What is the conditional probability that  $V$  is  $(0,0)$  given that  $V$  is  $(0,0)$  or  $(1,1)$ ?
- ▶ What is the conditional probability that  $X$  is 1 or 2 given that  $Y$  is 0 or 1?
- ▶ What is the probability that  $X$  is 1 or 2?
- ▶ What is the probability mass function of  $X \mid Y = 0$ ?
- ▶ What is the expected value of  $X \mid Y = 0$ ?

## Conditional Probability Example

$$\begin{aligned}\mathbb{P}(V \in \{(0, 0)\} \mid V \in \{(0, 0), (1, 1)\}) &= \frac{\mathbb{P}(V \in \{(0, 0)\} \cap \{(0, 0), (1, 1)\})}{\mathbb{P}(V \in \{(0, 0), (1, 1)\})} \\ &= \frac{0.10}{0.25} = 0.4\end{aligned}$$

$$\begin{aligned}\mathbb{P}(X \in \{1, 2\} \mid Y \in \{0, 1\}) &= \mathbb{P}(V \in \{1, 2\} \times \mathbb{R} \mid V \in \mathbb{R} \times \{0, 1\}) \\ &= \frac{\mathbb{P}(V \in \{(1, 0), (1, 1)\})}{\mathbb{P}(V \in \{(0, 0), (0, 1), (1, 0), (1, 1)\})} = \frac{0.45}{0.75} = 0.6\end{aligned}$$

$$\mathbb{P}(X \in \{1, 2\}) = \mathbb{P}(V \in \{1, 2\} \times \mathbb{R}) = 0.7$$

$$p_{X|Y=0}(x) = \frac{p_V(x, 0)}{\sum_{x' \in \{0, 1\}} p_V(x', 0)} = \frac{1}{0.4} p_V(x, 0) = \begin{cases} 0.25 & \text{if } x = 0 \\ 0.75 & \text{if } x = 1 \end{cases}$$

$$\mathbb{E}[X \mid Y = 0] = \sum_{x \in \{0, 1\}} x p_{X|Y=0}(x) = p_{X|Y=0}(1) = 0.75$$

## Change of Density

- ▶ **Convolution:** Let  $X$  and  $Y$  be independent random variables with pdfs  $p$  and  $q$ , respectively. Then, the pdf of  $Z = X + Y$  is given by the convolution of  $p$  and  $q$ :

$$[p * q](z) := \int p(z - y)q(y)dy = \int p(x)q(z - x)dx$$

- ▶ **Change of Density:** Let  $Y = f(X)$ . Then, with  $dy = \left| \det \left( \frac{df}{dx}(x) \right) \right| dx$ :

$$\begin{aligned} \mathbb{P}(Y \in A) &= \mathbb{P}(X \in f^{-1}(A)) = \int_{f^{-1}(A)} p_x(x)dx \\ &= \int_A \underbrace{\frac{1}{\left| \det \left( \frac{df}{dx}(f^{-1}(y)) \right) \right|}}_{p_y(y)} p_x(f^{-1}(y)) dy \end{aligned}$$

## Change of Density Example

- ▶ Let  $X \sim \mathcal{N}(0, \sigma^2)$  and  $Y = f(X) = \exp(X)$
- ▶ Note that  $f(x)$  is invertible  $f^{-1}(y) = \log(y)$
- ▶ The infinitesimal integration volumes for  $y$  and  $x$  are related by:

$$dy = \left| \det \left( \frac{df}{dx}(x) \right) \right| dx = \exp(x) dx$$

- ▶ Using change of density with  $A = [0, \infty)$  and  $f^{-1}(A) = (-\infty, \infty)$ :

$$\begin{aligned} \mathbb{P}(Y \in [0, \infty)) &= \int_{-\infty}^{\infty} \phi(x; 0, \sigma^2) dx = \int_0^{\infty} \frac{1}{\exp(\log(y))} \phi(\log(y); 0, \sigma^2) dy \\ &= \int_0^{\infty} \underbrace{\frac{1}{y} \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{1}{2} \frac{\log^2(y)}{\sigma^2}\right)}_{p(y)} dy \end{aligned}$$

## Change of Density Example

- ▶ Let  $V := (X, Y)$  be a random vector with pdf:

$$p_V(x, y) := \begin{cases} 2y - x & x < y < 2x \text{ and } 1 < x < 2 \\ 0 & \text{else} \end{cases}$$

- ▶ Let  $T := (M, N) = g(V) := \left(\frac{2X-Y}{3}, \frac{X+Y}{3}\right)$  be a function of  $V$

- ▶ Note that  $X = M + N$  and  $Y = 2N - M$  and, hence, the pdf of  $V$  is non-zero for  $0 < m < n/2$  and  $1 < m + n < 2$ . Also:

$$\det \left( \frac{dg}{dv} \right) = \det \begin{bmatrix} 2/3 & -1/3 \\ 1/3 & 1/3 \end{bmatrix} = \frac{1}{3}$$

- ▶ The pdf  $T$  is:

$$p_T(m, n) = \begin{cases} \frac{1}{|\det(\frac{dg}{dv}(m+n, 2n-m))|} p_V(m+n, 2n-m), & 0 < m < n/2 \text{ and} \\ & 1 < m+n < 2, \\ 0, & \text{else.} \end{cases}$$